Analogs of Hodge–Riemann relations in algebraic geometry, convex geometry and linear algebra

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Hodge-Riemann form

Let X be a compact Kähler *n*-manifold with a Kähler form ω .

Example

X is an algebraic manifold in projective space, and ω is a differential form defining the cohomology class Poincaré dual to a hyperplane section.

Let α be a (p, q)-form: the space of such forms is locally spanned by products of p holomorphic and q anti-holomorphic differentials. The *Hodge-Riemann form* is

$$q(\alpha) = C \int_X \alpha \wedge \overline{\alpha} \wedge \omega^{n-p-q}.$$

The coefficient C is ± 1 or $\pm i$, and depends only on p and q. (if α is dual to an analytic cycle σ , then this is the "projective degree" of the self-intersection σ^2)

Hodge-Riemann relations

• Suppose that $[\alpha] \neq 0$ is a *primitive class*, i.e.

$$[\alpha \wedge \omega^{n-p-q+1}] = 0.$$

• Then

$$q(\alpha) > 0.$$

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In particular, if a divisor σ on a projective surface has "degree"
0, then its self-intersection is negative (the *index theorem*).

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Hard Lefschetz theorem

The map

$$\wedge [\omega]^{n-p-q}: H^{p,q} \to H^{n-q,n-p}$$

is an *isomorphism* of vector spaces $(H^{p,q})$ is the (p,q)-cohomology space: closed (p,q)-forms modulo exact (p,q)-forms)

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$$A+B:=\{a+b\mid a\in A,\quad b\in B\}.$$

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Let A and B be convex sets in ℝⁿ. The Minkowsi sum A + B is defined as

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- We can think of *A* + *B* as the union of copies of *B* attached to every point of *A*.
- E.g. if B is the ball of radius ε , then A + B is the ε -neighborhood of A.



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- Let A and B be convex bodies in \mathbb{R}^n , then $\operatorname{Vol}(A+B)^{\frac{1}{n}} \geq \operatorname{Vol}(A)^{\frac{1}{n}} + \operatorname{Vol}(B)^{\frac{1}{n}}.$
- (i.e. the function $\operatorname{Vol}^{\frac{1}{n}}$ is *concave*).
- If B is the unit ball, this is a variant of the *isoperimetric inequality*: note that the surface area is the growth rate of volume of the ε-neighborhood.
- In general: isoperimetric inequality in *Minkowski geometry* (where *B* plays the role of the unit ball).

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Minkowski addition and the surface area

If we differentiate the volume of ε -neighborhood by ε at $\varepsilon = 0$, then we obtain the surface area (surface volume):

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Analogs in algebraic geometry

"Algebro-geometric" Brunn theorem (Khovanskii and Teissier, 70s):

 $V \subset \mathbb{P}_1 imes \mathbb{P}_2$ irreducible algebraic submanifold.

Then

$$\operatorname{Vol}(V)^{\frac{1}{n}} \geq \operatorname{Vol}(V_1)^{\frac{1}{n}} + \operatorname{Vol}(V_2)^{\frac{1}{n}},$$

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where V_1 and V_2 are projections of V on \mathbb{P}_1 and \mathbb{P}_2 , respectively.

Mixed volumes

The function of Volume is a homogeneous polynomial on convex sets in \mathbb{R}^n , i.e.

$$\operatorname{Vol}(\lambda_1 A_1 + \cdots + \lambda_n A_n)$$

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is a homogeneous polynomial in $\lambda_1, \ldots, \lambda_n$ of degree *n*, for $\lambda_1, \ldots, \lambda_n \ge 0$. *Mixed volume* $\operatorname{Vol}(A_1, \ldots, A_n)$ is the *polarization* of Vol (symmetric *n*-linear form s.t. $\operatorname{Vol}(A, \ldots, A) = \operatorname{Vol}(A)$).

Polarization

• The main idea of polarization is:

$$ab = \frac{(a+b)^2 - a^2 - b^2}{2}$$

(product can be expressed through squares).

• Similarly, for the mixed area:

$$\operatorname{Vol}_2(A,B) = rac{\operatorname{Vol}_2(A+B) - \operatorname{Vol}_2(A) - \operatorname{Vol}_2(B)}{2}.$$

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Minkowski theorem

The Brunn theorem is equivalent to the following inequality on mixed volumes:

$$\operatorname{Vol}(A, B, \underbrace{B, \ldots, B}_{n-2 \ times})^2 \ge \operatorname{Vol}(A, A, \underbrace{B, \ldots, B}_{n-2 \ times}) \cdot \operatorname{Vol}(B).$$

In other words, the bilinear form

$$\operatorname{Vol}(\cdot, \cdot, \underbrace{B, \dots, B}_{n-2 \ times})$$

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satisfies the reversed Cauchy-Schwartz inequality \Leftrightarrow it has positive index 1.

Hodge index theorem

This is related to the *Hodge index theorem*: the intersection form for divisors on a smooth compact projective surface has positive index 1, i.e.

$$(D_1 \cdot D_2)^2 \ge (D_1 \cdot D_1)(D_2 \cdot D_2), \quad D_1 > 0$$

More generally, for positive divisors D_1, \ldots, D_n on a compact projective manifold,

$$(D_1 \cdot D_2 \cdot D_3 \cdots D_n)^2 \ge (D_1 \cdot D_1 \cdot D_3 \cdots D_n)(D_2 \cdot D_2 \cdot D_3 \cdots D_n).$$

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(mixed Hodge index theorem — A. Khovanskii, B. Teissier)

Aleksandrov-Fenchel inequalities

Let A_1, \ldots, A_n be convex bodies. Then

$$\operatorname{Vol}(A_1, A_2, A_3, \dots, A_n)^2 \geq$$

 $\operatorname{Vol}(A_1, A_1, A_3, \ldots, A_n) \operatorname{Vol}(A_2, A_2, A_3, \ldots, A_n)$

[A. Aleksandrov, 1937] Aleksandrov gave two proofs of this theorem:

- through convex polytopes ("intersection theory on toric varieties"),
- 2. through elliptic differential operators ("Hodge theory")

Table of correspondence (beginning)

Minkowski inequality	Hodge index theorem
Aleksandrov–Fenchel	mixed Hodge index theorem
inequality	(A. Khovanskii, B. Teissier)
"Hodge–Riemann relations"	Hodge–Riemann relations
for simple polytopes	
(P. McMullen, V.T.)	
"mixed Hodge–Riemann	mixed Hodge–Riemann
relations" for simple	relations
polytopes (P. McMullen, V.T.)	(T. Dinh and V. Nguyên)

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Inequalities from Linear Algebra

Mixed discriminant det (A_1, \ldots, A_n) of symmetric matrices A_1, \ldots, A_n is the polarization of the discriminant (=determinant). The Aleksandrov inequality for mixed discriminants:

$$\det(A_1, A_2, A_3, \ldots, A_n)^2 \geq$$

$$det(A_1, A_1, A_3, \ldots, A_n) det(A_2, A_2, A_3, \ldots, A_n)$$

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for positive definite matrices A_1, \ldots, A_n . This is an infinitesimal version of both Aleksandrov–Fenchel inequality and the mixed Hodge index theorem.

Van der Waerden problem

The Aleksandrov inequality for mixed discriminants was used in a proof of the Van der Waerden conjecture on permanents of doubly stochastic matrices (Falikman, Egorychev). (an inequality for the probability of a random self-map of a finite set to be a permutation).

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Inequalities from Linear Algebra

Let
$$\omega_1, \ldots, \omega_{n-p-q+1}$$
 be positive $(1, 1)$ -forms on \mathbb{C}^n . Set $\Omega = \omega_1 \wedge \cdots \wedge \omega_{n-p-q}$. For any (p, q) -form $\alpha \neq 0$ such that $\alpha \wedge \Omega \wedge \omega_{n-p-q+1} = 0$,

$$C * (\alpha \wedge \overline{\alpha} \wedge \Omega) > 0$$

(V.T., 1998). This is a generalization of the Aleksandrov inequality for mixed discriminants.

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Mixed Hodge–Riemann relations

Let $\omega_1, \ldots, \omega_{n-p-q+1}$ be Kähler forms on a compact complex *n*-manifold X. Set $\Omega = \omega_1 \wedge \cdots \wedge \omega_{n-p-q}$. For any closed (but not exact) (p, q)-form α such that $[\alpha \wedge \Omega \wedge \omega_{n-p-q+1}] = 0$,

$$C\int_{X}\alpha\wedge\overline{\alpha}\wedge\Omega>0$$

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(T. Dinh and V. Nguyên, 2005).

This result was motivated by dynamics of holomorphic automorphisms.

Analogs of Hodge–Riemann relations for simple convex polytopes

- A convex polytope Δ ∈ ℝⁿ is said to be simple if exactly n facets meet at each vertex. Simple polytopes are stable under small perturbations of facets.
- A polytope analogous to Δ is any polytope obtained from Δ by parallel translations of facets, without changing the combinatorial type.

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Analogous polytopes



- The set of polytopes analogous to a given one, is stable under Minkowski addition and multiplication by positive numbers. This is a convex cone, which can be extended to a finite dimensional vector space.
- *Coordinates* in this space are *support numbers* (signed distances from the origin to support hyperplanes containing the facets).
- The space of all "virtual" polytopes analogous to a given one has the dimension *N* = the number of all facets.

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Volume polynomial

The restriction of the volume polynomial to the space of polytopes analogous to a simple polytope Δ can be expressed as a polynomial

$$\operatorname{Vol}_{\Delta}(h_1,\ldots,h_N)$$

in support numbers h_1, \ldots, h_N . Let H_1, \ldots, H_N be the support numbers of Δ . Introduce the operator

$$L_{\Delta} = \sum_{k=1}^{N} H_k \frac{\partial}{\partial h_k}$$

of differentiation along Δ . Then

$$\operatorname{Vol}_{\Delta} = \frac{1}{n!} L_{\Delta}^{n}(\operatorname{Vol}_{\Delta}).$$

Description of the "cohomology ring"

With each simple polytope Δ , one associates a "cohomology algebra". For lattice polytopes, it is isomorphic to the cohomology algebra of the corresponding toric variety:

$$A_{\Delta} = rac{\text{Diff. operators with const. coefficients } \alpha}{\alpha \text{Vol}_{\Delta} = 0}$$

(A. Khovanskii and A. Pukhlikov, unpublished) Poincaré duality and the Lefschetz operator look especially simple in this description.

Consider a differential operator α of order k with constant coefficients. The operator α is said to be *primitive*, if

$$L^{n-2k+1}_{\Delta}\alpha(\mathrm{Vol}_{\Delta})=0.$$

Equivalently, the polynomial αVol_{Δ} has zero of order $\geq k$ at point (H_1, \ldots, H_N) . If $\alpha \neq 0$ is primitive, then

$$(-1)^k \alpha^2 L^{n-2k}_{\Delta}(\operatorname{Vol}_{\Delta}) > 0.$$

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(P. McMullen 1993; in this form V.T. 1999)

- "Hodge-Riemann relations" for convex simple polytopes imply an analog of Hard Lefschetz theorem, which can be expressed as certain inequalities on combinatorial parameters of the polytope.
- For a simple convex *n*-polytope Δ, let *f_k*(Δ) be the number of all *k*-faces in Δ. The vector (*f*₀(Δ),...,*f_n*(Δ)) is called the *f*-vector of Δ.
- The *g*-theorem: An integer vector $(f_0, ..., f_n)$ is the *f*-vector of a simple *n*-polytope if and only if it satisfies certain explicit inequalities.
- An algebro-geometric proof: R. Stanley, 1980 (intersection cohomology for toric varieties), a convex-geometric proof: P. McMullen, 1993.

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 $\Lambda L_{n-2k+1}\alpha(\mathrm{Vol}_{\Delta})=0,$

where $\Lambda = L_{\Delta_1} \cdots L_{\Delta_{n-2k}}$. If $\alpha \neq 0$ is primitive, then

 $(-1)^k \alpha^2 \Lambda(\operatorname{Vol}_{\Delta}) > 0.$

(P. McMullen 1993; in this form V.T. 1999) This is a generalization of the Aleksandrov–Fenchel inequality.

Table of correspondence

Minkowski inequality	Hodge index theorem
Aleksandrov–Fenchel	mixed Hodge index theorem
inequality	(A. Khovanskii, B. Teissier)
"Hodge–Riemann relations"	Hodge–Riemann relations
for simple polytopes	
(P. McMullen, V.T.)	
"mixed Hodge–Riemann	mixed Hodge–Riemann
relations" for simple	relations
polytopes (P. McMullen, V.T.)	(T. Dinh and V. Nguyên)
"Hodge–Riemann relations"	Hodge–Riemann relations
for arbitrary polytopes	in intersection cohomology
(K.Karu,)	(M. Saito,)

- Combinatorial intersection cohomology (P. Bressler and V. Lunts; G. Barthel, J.-P. Brasselet, K.-H. Fiesler and L. Kaup): for rational polytopes, isomorphic to intersection cohomology of the corresponding toric varieties.
- First, one defines a sheaf on the dual fan (regarded as a finite topological space), which is an analog of the *equivariant intersection cohomology sheaf* (in the sense of J. Bernstein and V. Lunts).
- The combinatorial intersection cohomology is a certain quotient of the space of global sections.
- K. Karu (2003) proved Hodge–Riemann relations in combinatorial intersection cohomology of arbitrary polytopes.

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